F20RO Intelligent Robotics

**COURSE DETAILS**

- **Course Code:** F20RO
- **Full Course Title:** Intelligent Robotics
- **SCQF Level:** 10
- **SCAF Credits:** 15
- **Available as Elective:** No

**DELIVERY LEVEL**

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<th>Undergraduate:</th>
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<th>Postgraduate Taught:</th>
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<th>Postgraduate Research:</th>
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**Additional Information:**

**COURSE AIMS**

To introduce students to concepts and techniques used in robotics and applications ranging from industrial automation to robotic companions.

To understand the basic concepts used in evolutionary, swarm and other bio-inspired robotics.

To understand the basic concepts used in developmental robotics and human-robot interaction.

To gain exposure to the main issues involved in building intelligent robot controllers.

**LEARNING OUTCOMES – SUBJECT MASTERY**

- To appreciate the basic concepts of automation and intelligent robotics.
- To develop detailed understanding of the geometries of industrial manipulators.
- To develop detailed understanding of the architectures of autonomous guided vehicles (AGVs).
- To develop detailed understanding of interfacing & control issues of manipulator arms and AGVs.
- To explore the applications and implications of automation and human-robot interaction.
- To appreciate the different forms and uses of various sensor technologies, including multi-modal sensing.
- To develop detailed understanding of the architecture of behaviour-based robotics (BBR), evolutionary robotics and swarm robotics.
- To explore the collaboration and ethical issues of human-robot interaction.
- To make informed judgements about appropriate methodologies for developing and evaluating robotics applications.

**LEARNING OUTCOMES – PERSONAL ABILITIES**

- To critically analyse various paradigms and architectures.
- To appreciate the real-world constraints imposed on technical skills.
- To offer professional insights into the financial imperatives which apply to the introduction of new technology.
- To offer ethical insights into the introduction of new robotics technology.

**SYLLABUS**

- Fundamentals of Manipulators - Geometry, kinematics, control and programming.
- Basics of Mobile Robots - Mapping, path planning and navigation.
- Behaviour Based Robotics - Evolutionary, swarm and other bio-inspired robotics.
## COURSE RELATIONSHIPS

<table>
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<tr>
<th>Course Code</th>
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<tbody>
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<td>F29AI</td>
<td>9</td>
<td>Artificial Intelligence and Intelligent Agents</td>
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<td>Pre-Requisite</td>
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## LOCATION AND ASSESSMENT METHODS

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